MIPS Assembly Language Programming

COE 308

Computer Architecture
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Presentation Outline

- Assembly Language Statements
- ❖ Assembly Language Program Template
- Defining Data
- Memory Alignment and Byte Ordering
- System Calls
- Procedures
- Parameter Passing and the Runtime Stack

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Assembly Language Statements

- Three types of statements in assembly language
 - → Typically, one statement should appear on a line
- 1. Executable Instructions
 - ♦ Generate machine code for the processor to execute at runtime
 - ♦ Instructions tell the processor what to do
- 2. Pseudo-Instructions and Macros
 - ♦ Translated by the assembler into real instructions
 - ♦ Simplify the programmer task
- 3. Assembler Directives
 - ♦ Provide information to the assembler while translating a program
 - ♦ Used to define segments, allocate memory variables, etc.
 - ♦ Non-executable: directives are not part of the instruction set

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Instructions

- Assembly language instructions have the format:
 - [label:] mnemonic [operands] [#comment]
- Label: (optional)
 - ♦ Marks the address of a memory location, must have a colon
 - → Typically appear in data and text segments
- Mnemonic
 - ♦ Identifies the operation (e.g. add, sub, etc.)
- Operands
 - ♦ Specify the data required by the operation
 - ♦ Operands can be registers, memory variables, or constants
 - Most instructions have three operands

L1: addiu \$t0, \$t0, 1

#increment \$t0

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Comments

- Comments are very important!
 - ♦ Explain the program's purpose
 - ♦ When it was written, revised, and by whom
 - ♦ Explain data used in the program, input, and output
 - ♦ Explain instruction sequences and algorithms used
 - ♦ Comments are also required at the beginning of every procedure
 - Indicate input parameters and results of a procedure
 - Describe what the procedure does
- Single-line comment
 - ♦ Begins with a hash symbol # and terminates at end of line

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Program Template

Title: Filename: # Author: Date: # Description: # Input: # Output: .text .globl main # main program entry main: li \$v0, 10 # Exit program syscall

.DATA, .TEXT, & .GLOBL Directives

.DATA directive

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- ♦ Defines the data segment of a program containing data
- ♦ The program's variables should be defined under this directive
- ♦ Assembler will allocate and initialize the storage of variables

❖ .TEXT directive

♦ Defines the code segment of a program containing instructions

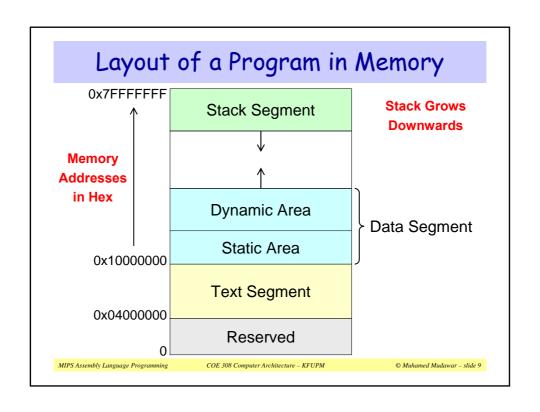
.GLOBL directive

- ♦ Declares a symbol as global
- ♦ Global symbols can be referenced from other files
- ♦ We use this directive to declare *main* procedure of a program

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Data Definition Statement

- Sets aside storage in memory for a variable
- May optionally assign a name (label) to the data
- ❖ Syntax:

[name:] directive initializer [, initializer] . . .







var1: .W

WORD

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All initializers become binary data in memory

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Data Directives

- ❖ .BYTE Directive
 - ♦ Stores the list of values as 8-bit bytes
- .HALF Directive
 - ♦ Stores the list as 16-bit values aligned on half-word boundary
- .WORD Directive
 - ♦ Stores the list as 32-bit values aligned on a word boundary
- .FLOAT Directive
 - ♦ Stores the listed values as single-precision floating point
- ❖ .DOUBLE Directive
 - ♦ Stores the listed values as double-precision floating point

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String Directives

* .ASCII Directive

♦ Allocates a sequence of bytes for an ASCII string

❖ .ASCIIZ Directive

- ♦ Same as .ASCII directive, but adds a NULL char at end of string
- ♦ Strings are null-terminated, as in the C programming language

❖ .SPACE Directive

♦ Allocates space of n uninitialized bytes in the data segment

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Examples of Data Definitions

.DATA

var1: .BYTE 'A', 'E', 127, -1, '\n'

var2: .HALF -10, 0xfffff

var3: .WORD 0x12345678

var4: .FLOAT 12.3, -0.1

var5: .DOUBLE 1.5e-10

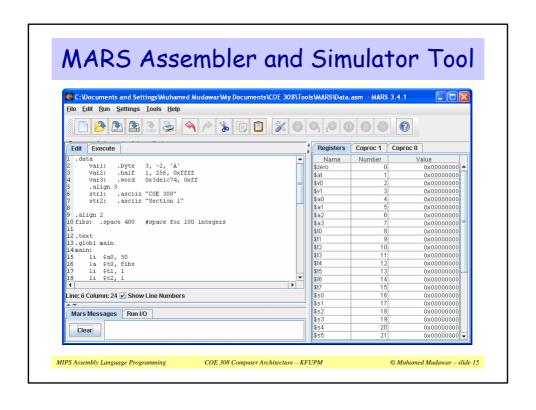
str1: .ASCII "A String\n"

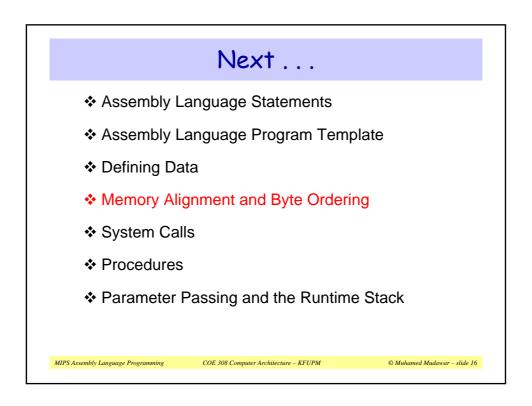
str2: .ASCIIZ "NULL Terminated String"

array: .SPACE 100

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Memory Alignment

- Memory is viewed as an array of bytes with addresses
 - ♦ Byte Addressing: address points to a byte in memory
- Words occupy 4 consecutive bytes in memory
 - ♦ MIPS instructions and integers occupy 4 bytes
- ❖ Alignment: address is a multiple of size
 - ♦ Word address should be a multiple of 4
 - Least significant 2 bits of address should be 00
 - ♦ Halfword address should be a multiple of 2



- .ALIGN n directive
 - ♦ Aligns the next data definition on a 2ⁿ byte boundary

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Symbol Table

- Assembler builds a symbol table for labels (variables)
 - ♦ Assembler computes the address of each label in data segment
- ❖ Example
 .DATA

Symbol Table

' ing\n" 678	Label	Address					
	var1	0x10010000					
	str1	0x10010003					
	var2	0x10010010					
	var3	0x10010018					

var1:	.BYTE	1, 2,'Z'
str1:	.ASCIIZ	"My String\n"
var2:	.WORD	0x12345678
.ALIGN	3	
var3:	.HALF	1000

var1	¬			str1													
0x10010000	1	2	'Z'	'M'	'y'	1 1	'S'	't'	'r'	Ψ	'n'	'g'	'\n'	0	0	0	Unused
0x10010010	0x	123	456	78	0	0	0	0	10	00							
var2 (aligned)	₫					Unu	ısed		L	var3	(add	dress	s is n	nultip	ole o	f 8)	

Byte Ordering and Endianness

- Processors can order bytes within a word in two ways
- Little Endian Byte Ordering
 - ♦ Memory address = Address of least significant byte



- Big Endian Byte Ordering
 - ♦ Memory address = Address of most significant byte



MIPS can operate with both byte orderings

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System Calls

- Programs do input/output through system calls
- MIPS provides a special syscall instruction
 - ♦ To obtain services from the operating system
 - ♦ Many services are provided in the SPIM and MARS simulators
- Using the syscall system services
 - ♦ Load the service number in register \$v0
 - ♦ Load argument values, if any, in registers \$a0, \$a1, etc.
 - ♦ Issue the syscall instruction
 - ♦ Retrieve return values, if any, from result registers

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Syscall Services

Service	\$v0	Arguments / Result					
Print Integer	1	Sa0 = integer value to print					
Print Float	2	Sf12 = float value to print					
Print Double	3	\$f12 = double value to print					
Print String	4	\$a0 = address of null-terminated string					
Read Integer	5	\$v0 = integer read					
Read Float	6	\$f0 = float read					
Read Double	7	\$f0 = double read					
Read String	8	\$a0 = address of input buffer					
	\$a1 = maximum number of characters to read						
Exit Program	10						
Print Char	11	\$a0 = character to print					
Read Char	12	\$a0 = character read Supported by MARS					

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Reading and Printing an Integer

```
.text
.globl main
main:
                           # main program entry
  li $v0,5
                           # Read integer
                           # $v0 = value read
  syscall
 move $a0, $v0
                          # $a0 = value to print
                          # Print integer
     $v0, 1
  syscall
  li $v0, 10
                          # Exit program
  syscall
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```

Reading and Printing a String

```
# array of 10 bytes
 str: .space 10
.globl main
                   # main program entry
main:
    $a0, str
                   # $a0 = address of str
 li $a1, 10
                   # $a1 = max string length
 li $v0,8
                   # read string
 syscall
                # Print string str
     $v0, 4
 syscall
     $v0, 10
                   # Exit program
 syscall
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```

Program 1: Sum of Three Integers

```
# Sum of three integers
# Objective: Computes the sum of three integers.
    Input: Requests three numbers.
   Output: Outputs the sum.
.data
prompt: .asciiz
                "Please enter three numbers: \n"
                "The sum is: "
.text
.globl main
main:
    la
       $a0,prompt
                       # display prompt string
    li
       $v0,4
    syscall
         $v0,5
                         # read 1st integer into $t0
    syscall
    move $t0,$v0
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```

Sum of Three Integers - Slide 2 of 2

```
$v0,5
                         # read 2nd integer into $t1
syscall
move $t1,$v0
      $v0,5
                        # read 3rd integer into $t2
syscall
move $t2,$v0
addu $t0,$t0,$t1
                         # accumulate the sum
addu $t0,$t0,$t2
     $a0,sum_msg
                         # write sum message
     $v0,4
syscall
move $a0,$t0
                         # output sum
li $v0,1
syscall
      $v0,10
                         # exit
syscall
```

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Program 2: Case Conversion

```
# Objective: Convert lowercase letters to uppercase
    Input: Requests a character string from the user.
    Output: Prints the input string in uppercase.
.data
                         "Please type your name: "
name_prompt: .asciiz
out_msg: .asciiz
                         "Your name in capitals is: "
           .space 31
                        # space for input string
in name:
.globl main
main:
         $a0,name_prompt # print prompt string
    li
        $v0,4
    syscall
     la
          $a0,in name
                       # read the input string
          $a1,31
                         # at most 30 chars + 1 null char
     li
          $v0,8
     syscall
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```

Case Conversion - Slide 2 of 2

```
$a0,out_msg
                              # write output message
      li
            $v0,4
      syscall
      la
           $t0,in_name
loop:
            $t1,($t0)
      beqz $t1,exit_loop
                            # if NULL, we are done
      blt $t1,'a',no_change
      bgt $t1,'z',no_change
                             # convert to uppercase: 'A'-'a'=-32
      addiu $t1,$t1,-32
      sb
            $t1,($t0)
no_change:
      addiu $t0,$t0,1
                             # increment pointer
exit_loop:
     la
            $a0,in name
                             # output converted string
            $v0,4
      syscall
      li
            $v0,10
                              # exit
      syscall
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```

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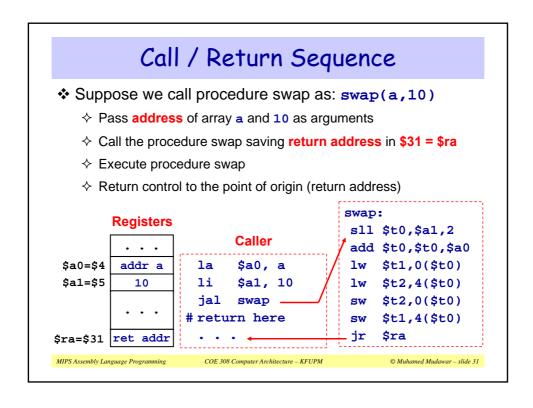
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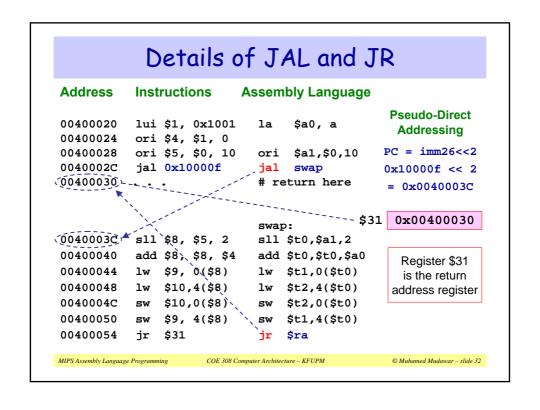
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Procedures

- Consider the following swap procedure (written in C)
- Translate this procedure to MIPS assembly language

```
void swap(int v[], int k)
 { int temp;
     temp = v[k]
                          swap:
     v[k] = v[k+1];
                           sll $t0,$a1,2
                                               # $t0=k*4
     v[k+1] = temp;
                           add $t0,$t0,$a0 # $t0=v+k*4
 }
                           lw $t1,0($t0)
                                               # $t1=v[k]
 Parameters:
                           lw $t2,4($t0)
                                               # $t2=v[k+1]
                           sw $t2,0($t0)
                                               \# v[k]=$t2
 a0 = Address of v[]
 $a1 = k, and
                           sw $t1,4($t0)
                                               # v[k+1]=$t1
 Return address is in $ra
                                $ra
                                               # return
                           jr
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```





Instructions for Procedures

- ❖ JAL (Jump-and-Link) used as the call instruction
 - ♦ Save return address in \$ra = PC+4 and jump to procedure
 - ♦ Register \$ra = \$31 is used by JAL as the return address
- ❖ JR (Jump Register) used to return from a procedure
 - → Jump to instruction whose address is in register Rs (PC = Rs)
- JALR (Jump-and-Link Register)
 - ♦ Save return address in Rd = PC+4, and
 - ♦ Jump to procedure whose address is in register Rs (PC = Rs)
 - ♦ Can be used to call methods (addresses known only at runtime)

Instruction		Meaning	Format							
jal	label	\$31=PC+4, jump	$op^6 = 3$	imm ²⁶						
jr	Rs	PC = Rs	$op^6 = 0$	rs ⁵	0	0	0	8		
jalr	Rd, Rs	Rd=PC+4, PC=Rs	$op^6 = 0$	rs ⁵	0	rd ⁵	0	9		

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Parameter Passing

- Parameter passing in assembly language is different
 - ♦ More complicated than that used in a high-level language
- In assembly language
 - ♦ Place all required parameters in an accessible storage area
 - ♦ Then call the procedure
- Two types of storage areas used
 - ♦ Registers: general-purpose registers are used (register method)
 - ♦ Memory: stack is used (stack method)
- Two common mechanisms of parameter passing
 - ♦ Pass-by-value: parameter value is passed
 - ♦ Pass-by-reference: address of parameter is passed

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Parameter Passing - cont'd

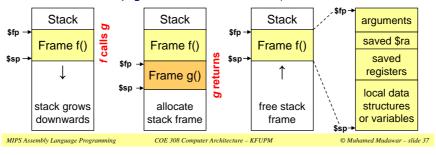
- By convention, register are used for parameter passing
 - ♦ \$a0 = \$4 ... \$a3 = \$7 are used for passing arguments
 - \Rightarrow \$v0 = \$2 .. \$v1 = \$3 are used for result values
- ❖ Additional arguments/results can be placed on the stack
- Runtime stack is also needed to ...
 - ♦ Store variables / data structures when they cannot fit in registers
 - ♦ Save and restore registers across procedure calls
 - ♦ Implement recursion
- Runtime stack is implemented via software convention
 - ♦ The stack pointer \$sp = \$29 (points to top of stack)
 - ♦ The frame pointer \$fp = \$30 (points to a procedure frame)

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Stack Frame

- Stack frame is the segment of the stack containing ...
 - ♦ Saved arguments, registers, and local data structures (if any)
- Called also the activation frame or activation record
- Frames are pushed and popped by adjusting ...
 - ♦ Stack pointer \$sp = \$29 and Frame pointer \$fp = R30
 - ♦ Decrement \$sp to allocate stack frame, and increment to free

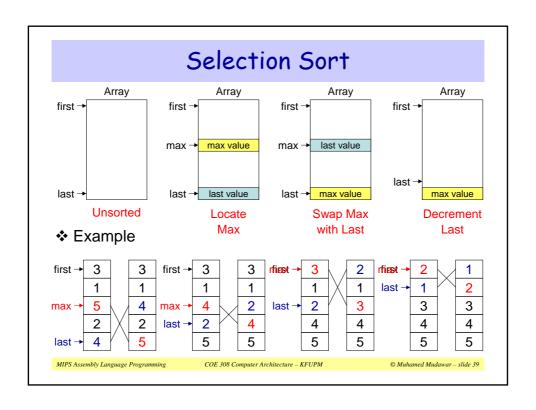


Preserving Registers

- Need to preserve registers across a procedure call
 - ♦ Stack can be used to preserve register values
- Which registers should be saved?
 - → Registers modified by the called procedure, and
 - ♦ Still used by the calling procedure
- Who should preserve the registers?
 - Called Procedure: preferred method for modular code
 - Register preservation is done inside the called procedure
 - ♦ By convention, registers \$s0, \$s1, ..., \$s7 should be preserved
 - ♦ Also, registers \$sp, \$fp, and \$ra should also be preserved

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Selection Sort Procedure # Objective: Sort array using selection sort algorithm Input: \$a0 = pointer to first, \$a1 = pointer to last Output: array is sorted in place sort: addiu \$sp, \$sp, -4 # allocate one word on stack \$ra, 0(\$sp) # save return address on stack # call max procedure top: jal lw \$t0, 0(\$a1) # \$t0 = last value \$t0, 0(\$v0) # swap last and max values sw \$v1, 0(\$a1) addiu \$a1, \$a1, -4 # decrement pointer to last bne \$a0, \$a1, top # more elements to sort \$ra, 0(\$sp) # pop return address addiu \$sp, \$sp, 4 jr \$ra # return to caller

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Max Procedure

```
# Objective: Find the address and value of maximum element
     Input: $a0 = pointer to first, $a1 = pointer to last
    Output: $v0 = pointer to max, $v1 = value of max
max: move $v0, $a0
                         # max pointer = first pointer
           $v1, 0($v0)
                        # $v1 = first value
     lw
           $a0, $a1, ret # if (first == last) return
     beq
     move $t0, $a0
                         # $t0 = array pointer
loop: addi $t0, $t0, 4
                         # point to next array element
           $t1, 0($t0)
                         # $t1 = value of A[i]
           $t1, $v1, skip # if (A[i] <= max) then skip
     ble
     move $v0, $t0
                          # found new maximum
     move $v1, $t1
skip: bne
           $t0, $a1, loop # loop back if more elements
ret: jr
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```

Example of a Recursive Procedure

int fact(int n) { if (n<2) return 1; else return (n*fact(n-1)); }

```
fact: slti
             $t0,$a0,2
                          # (n<2)?
             $t0,$0,else
      beq
                         # if false branch to else
      1i
             $v0,1
                          # $v0 = 1
                          # return to caller
      jr
             $ra
else: addiu
             $sp,$sp,-8 # allocate 2 words on stack
             $a0,4($sp) # save argument n
      sw
      sw
             $ra,0($sp)
                         # save return address
      addiu
             $a0,$a0,-1
                          # argument = n-1
      jal
             fact
                          # call fact(n-1)
      lw
             $a0,4($sp)
                          # restore argument
                          # restore return address
      1w
             $ra,0($sp)
      mul
             v0,a0,v0 # v0 = n*fact(n-1)
      addi
             $sp,$sp,8
                          # free stack frame
      jr
             $ra
                          # return to caller
```

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